

# AN INTRODUCTION TO SYMPLECTIC GEOMETRY

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## 1. OVERVIEW OVER THE BASIC NOTIONS IN SYMPLECTIC GEOMETRY

**Definition 1.1.** Let  $V$  be a  $m$ -dimensional  $\mathbb{R}$  vector space and let  $\Omega : V \times V \rightarrow \mathbb{R}$  be a bilinear map. We say  $\Omega$  is **skew-symmetric** if  $\Omega(u, v) = -\Omega(v, u)$ , for all  $u, v \in V$ .

**Theorem 1.1.** Let  $\Omega$  be a skew-symmetric bilinear map on  $V$ . Then there is a basis  $u_1, \dots, u_k, e_1, \dots, e_n, f_1, \dots, f_n$  of  $V$  s.t.

$$\begin{aligned} \Omega(u_i, v) &= 0, & \forall i \text{ and } \forall v \in V \\ \Omega(e_i, e_j) &= 0 = \Omega(f_i, f_j), & \forall i, j \\ \Omega(e_i, f_j) &= \delta_{ij}, & \forall i, j. \end{aligned}$$

In matrix notation with respect to this basis we have

$$\Omega(u, v) = u^T \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & id \\ 0 & -id & 0 \end{pmatrix} v.$$

In particular we have  $\dim(V) = m = k + 2n$ .

*Proof.* The proof is a skew-symmetric version of the Gram-Schmidt process. First let

$$U := \{u \in V \mid \Omega(u, v) = 0 \text{ for all } v \in V\},$$

and choose a basis  $u_1, \dots, u_k$  for  $U$ . Now choose a complementary space  $W$  s.t.  $V = U \oplus W$ . Let  $e_1 \in W$ , then there is a  $f_1 \in W$  s.t.  $\Omega(e_1, f_1) \neq 0$  and we can assume that  $\Omega(e_1, f_1) = 1$ . Let

$$\begin{aligned} W_1 &= \text{span}(e_1, f_1) \\ W_1^\Omega &= \{w \in W \mid \Omega(w, v) = 0 \text{ for all } v \in W_1\}. \end{aligned}$$

We claim that  $W = W_1 \oplus W_1^\Omega$ : Suppose that  $v = ae_1 + bf_1 \in W_1 \cap W_1^\Omega$ . We get that

$$\begin{aligned} 0 &= \Omega(v, e_1) = -b \\ 0 &= \Omega(v, f_1) = a \end{aligned}$$

and therefore  $v = 0$ . Now let  $v \in W$ . We have that  $\Omega(v, e_1) = c$  and  $\Omega(v, f_1) = d$ . And therefore

$$v = \underbrace{(-cf_1 + de_1)}_{\in W_1} + \underbrace{(v + cf_1 - de_1)}_{\in W_1^\Omega}.$$

This shows the claim. Now we go on: we pick  $e_2, f_2 \in W_1^\Omega$  with  $\Omega(e_2, f_2) = 1$ . Let  $W_2 = \text{span}(e_2, f_2)$ . With the same arguments as above we obtain a decomposition

$$V = U \oplus W_1 \oplus \dots \oplus W_n.$$

Note that the  $e_i, f_i$  always come in pairs, because if one of the  $W_i^\Omega$  would be one dimensional it would actually lie in  $U$ . But now we have our desired decomposition.  $\square$

**Remark.** We will call  $n$  the rank of the bilinear map  $\Omega$ .

**Definition 1.2.** A skew-symmetric bilinear map is called symplectic (or non-degenerate) if  $U = \{0\}$  ( $U$  as above). The map  $\Omega$  is then called a linear symplectic structure on  $V$  and  $(V, \Omega)$  is called a symplectic vector space.

**Corollary 1.1.1.** *As an immediate Corollary of Theorem 1.1 we get that  $\dim(V) = 2n$  since  $\dim(U) = 0$ . Choosing a basis as in the Theorem we have that*

$$\Omega(u, v) = u^T \begin{pmatrix} 0 & id \\ -id & 0 \end{pmatrix} v.$$

The basis  $e_1, \dots, e_n, f_1, \dots, f_n$  is called a symplectic basis.

**Definition 1.3.** We have different kind of subspaces of a symplectic vector space. Let  $W$  be a subspace of  $(V, \Omega)$ . Denote

$$W^\Omega := \{v \in V \mid \Omega(v, w) = 0 \ \forall w \in W\}$$

- 1) A subspace  $W \subset V$  is called **symplectic** if  $W \cap W^\Omega = \emptyset$  if and only if  $\Omega|_W$  is non-degenerate. For example  $\text{span}(e_i, f_i)$  is a symplectic subspace.
- 2) A subspace  $W \subset V$  is called **isotropic** if  $W \subset W^\Omega$  if and only if  $\Omega|_W \equiv 0$ . For example  $\text{span}(e_1, e_2)$  is isotropic.
- 3) A subspace is called **coisotropic** if  $W^\Omega \subset W$  if and only if  $W^\Omega$  is isotropic. For example codimension 1 subspaces are coisotropic.
- 4) A subspace is called **Lagrangian** if it is isotropic and  $\dim(W) = \frac{1}{2} \dim(V)$  if and only if  $W^\Omega = W$ .

**Definition 1.4.** Let  $(V, \Omega), (V', \Omega')$  be two symplectic vector spaces. A linear map  $\varphi : V \rightarrow V'$  is called a **symplectomorphism** if  $\Omega = \varphi^* \Omega'$ . If a symplectomorphism exists  $(V, \Omega)$  and  $(V', \Omega')$  are called symplectomorphic.

**Lemma 1.2.** *A linear map  $\varphi : V \rightarrow V$  is a symplectomorphism iff the graph*

$$\Gamma_\varphi := \{(v, \varphi(v)) \in V \times V \mid v \in V\}$$

*is a Lagrangian subspace of  $(V \times V, (-\Omega) \times \Omega)$ , where  $(-\Omega) \times \Omega((v, v'), (w, w')) = -\Omega(v, w) + \Omega(v', w')$ .*

*Proof.* Let  $\varphi$  be a symplectomorphism. Then we have  $\Gamma_\varphi \subset \Gamma_\varphi^\Omega$ , since

$$\begin{aligned} (-\Omega) \times \Omega((v, \varphi(v)), (w, \varphi(w))) &= -\Omega(v, w) + \Omega(\varphi(v), \varphi(w)) \\ &= -\Omega(v, w) + \Omega(v, w) \\ &= 0. \end{aligned}$$

The dimension of  $\Gamma_\varphi$  is equal to the dimension of  $V$ , which finishes the first direction.

Now let  $\Gamma_\varphi$  be a Lagrangian subspace it follows that

$$0 = -\Omega(v, w) + \Omega(\varphi(v), \varphi(w)),$$

for all  $v, w \in V$ . This shows that  $\varphi$  is an isomorphism and  $\Omega = \varphi^* \Omega$ .  $\square$

We now turn to manifolds. Let  $M$  be a manifold and  $\omega$  be a differential 2-form, i.e. for  $p \in M$  we have that  $\omega_p : T_p M \times T_p M \rightarrow \mathbb{R}$  is a skew-symmetric bilinear map and  $\omega_p$  varies smoothly in  $p$ . We say  $\omega$  is closed if it satisfies  $d\omega = 0$ , i.e.  $\omega$  is a cycle in the de Rham-complex.

**Definition 1.5.** The 2-form  $\omega$  is symplectic if  $\omega$  is closed and  $\omega_p$  is a symplectic bilinear map on  $T_p M$  for all  $p \in M$ . If  $\omega$  is symplectic we obtain

$$\dim(M) = \dim(T_p M) = 2n.$$

A *symplectic manifold* is a pair  $(M, \omega)$  where  $M$  is a manifold and  $\omega$  is a symplectic form.

**Example 1.1.**

- The prototype for a symplectic manifold is  $\mathbb{R}^{2n}$  with linear coordinates  $x_1, \dots, x_n, y_1, \dots, y_n$ . The form

$$\omega = \sum_{i=1}^n dx_i \wedge dy_i$$

is symplectic and the set

$$\left\{ \frac{\partial}{\partial x_1}(p), \dots, \frac{\partial}{\partial x_n}(p), \frac{\partial}{\partial y_1}(p), \dots, \frac{\partial}{\partial y_n}(p) \right\}$$

is a symplectic basis of  $T_p M$ .

- In a similar spirit we have that  $\mathbb{C}^n$  is a symplectic manifold with linear coordinates  $z_1, \dots, z_n$  and symplectic form

$$\omega = \frac{i}{2} \sum_{k=1}^n dz_k \wedge d\bar{z}_k.$$

- Let  $M = S^2$  regarded as the set of unit vectors in  $\mathbb{R}^3$ . We have a form

$$\omega(u, v) = \langle p, u \times v \rangle$$

for  $u, v \in T_p S^2 = \{p\}^\perp$ . This form is closed since it is of top degree. It is non-degenerate since for example  $u \neq 0$  and  $v = u \times p$  gives  $\omega(u, v) \neq 0$ .

- The higher dimensional spheres  $S^{2n}$  with  $n > 1$  don't carry a symplectic structure. This follows from the general fact, that the even dimensional De-Rham cohomology groups  $H_{dR}^k(M)$  of a compact symplectic manifold  $M$  are not zero.
- Any non-orientable Manifold doesn't carry a symplectic structure, since  $\omega^n$  is a non-vanishing form and therefore gives a orientation on any symplectic manifold.

**Definition 1.6.** Let  $(M_1, \omega_1), (M_2, \omega_2)$  be two  $2n$  dimensional symplectic manifolds. Let  $\varphi : M_1 \rightarrow M_2$  be a diffeomorphism. Then  $\varphi$  is a symplectomorphism if  $\omega_1 = \varphi^* \omega_2$ .

**Theorem 1.3.** Let  $(m, \omega)$  be a  $2n$  dimensional symplectic manifold, and let  $p \in M$  be any point in  $M$ . Then there is a coordinate chart  $(U, \varphi = x_1, \dots, x_n, y_1, \dots, y_n)$  centered at  $p$  (i.e.  $\varphi(p) = 0$ ) s.t.

$$\omega = \sum_{i=1}^n dx_i \wedge dy_i,$$

locally on  $U$ . Such a chart is called a **Darboux chart**.

### Example 1.2. The Cotangent Bundle

Let  $X$  be any  $n$ -dimensional manifold and let  $M = T^*X$  be its cotangent bundle. Let  $(U, x_1, \dots, x_n)$  be a chart on  $X$ . Then the differentials  $(dx_1)_x, \dots, (dx_n)_x$  form a basis of  $T_x^*X$  for all  $x \in U$ . For  $\xi \in T_x^*X$  we can write  $\xi = \sum_{i=1}^n \xi_i (dx_i)_x$ . This induces a coordinate chart on  $T^*U \subset T^*X$

$$\begin{aligned} T^*U &\rightarrow \mathbb{R}^{2n} \\ (x, \xi) &\mapsto (x_1, \dots, x_n, \xi_1, \dots, \xi_n). \end{aligned}$$

For two charts  $(U, \varphi = x_1, \dots, x_n), (V, \psi = x'_1, \dots, x'_n)$  on  $X$  for  $x \in U \cap V$  we have

$$(dx'_i)_x = \sum_{j=1}^n \frac{\partial(\psi \circ \varphi^{-1})_i}{\partial x_j}(\varphi(x))(dx_j)_x$$

and therefore for  $\xi \in T_x^*X$  we have

$$(1) \quad \xi = \sum_{i=1}^n \xi_i (dx_i)_x = \sum_{j=1}^n \xi'_j (dx'_j)_x$$

where  $\xi'_j = \sum_{i=1}^n \xi_i \frac{\partial(\psi \circ \varphi^{-1})_i}{\partial x_j}(\varphi(x))$ . This is a smooth function and thus the cotangent bundle is smooth. We now have the following 2-form on  $T^*U$ ,

$$\omega = \sum_{i=1}^n dx_i \wedge d\xi_i.$$

This 2-form is closed since we have a 1-form on  $T^*U$ ,

$$\alpha = \sum_{i=1}^n \xi_i dx_i$$

with  $-d\alpha = \omega$ . We claim that  $\alpha$  is independent of the choice of coordinates. This follows directly from formula (1), since for 2 coordinate charts  $(T^*U, x_1, \dots, x_n, \xi_1, \dots, \xi_n), (T^*V, x'_1, \dots, x'_n, \xi'_1, \dots, \xi'_n)$  we have that

$$\alpha = \sum_{i=1}^n \xi_i dx_i = \sum_{j=1}^n \xi'_j dx'_j = \alpha'$$

on  $T^*U \cap T^*V$ . So  $\alpha$  gives a 1-form on  $T^*X$  called the **tautological form** or **Liouville 1-form**, the 2-form  $\omega$  is called the **canonical symplectic form**.

### Example 1.3. Complex projective Space $\mathbb{P}_{\mathbb{C}}^n$

Consider the linear coordinates  $z_1, \dots, z_n$  on  $\mathbb{C}^n \setminus \{0\}$ , where  $z_j = x_j + iy_j$ . We will use the complex valued forms

$$dz_j := dx_j + idy_j, \quad d\bar{z}_j := dx_j - idy_j$$

and the differential operators

$$\frac{\partial}{\partial z_j} := \frac{1}{2} \left( \frac{\partial}{\partial x_j} - i \frac{\partial}{\partial y_j} \right), \quad \frac{\partial}{\partial \bar{z}_j} := \frac{1}{2} \left( \frac{\partial}{\partial x_j} + i \frac{\partial}{\partial y_j} \right)$$

acting on the space of complex valued smooth functions on  $\mathbb{C}^n \setminus \{0\}$ . In this notation we can write the differential of a smooth function  $f : \mathbb{C}^n \setminus \{0\} \rightarrow \mathbb{C}$  as  $df = \partial f + \bar{\partial} f$ , where

$$\partial f := \sum_{j=1}^n \frac{\partial f}{\partial z_j} dz_j, \quad \bar{\partial} f := \sum_{j=1}^n \frac{\partial f}{\partial \bar{z}_j} d\bar{z}_j.$$

We also need the 2-form

$$\partial \bar{\partial} f = \sum_{j,k=1}^n \frac{\partial^2 f}{\partial z_j \partial \bar{z}_k} dz_j \wedge d\bar{z}_k$$

We can now define a 2-form on  $\mathbb{C}^n \setminus \{0\}$ , by

$$\begin{aligned} \tilde{\omega}_{FS} &:= \frac{i}{2} \partial \bar{\partial} \log(|z|^2) \\ &= \frac{i}{2|z|^4} \sum_{j,k=1}^n (|z|^2 dz_k \wedge d\bar{z}_k - \bar{z}_j z_k dz_j \wedge d\bar{z}_k). \end{aligned}$$

Then there exists a unique real-valued 2-form  $\omega_{FS}$  on  $\mathbb{P}_{\mathbb{C}}^{n-1}$  s.t.

$$\tilde{\omega}_{FS} = \pi^* \omega_{FS}.$$

Where  $\pi : \mathbb{C}^n \rightarrow \mathbb{P}_{\mathbb{C}}^{n-1}$  is the usual projection map. We call  $\omega_{FS}$  the **Fubini Study form** on  $\mathbb{P}_{\mathbb{C}}^{n-1}$ . It will follow from the Marsden-Meyer-Weinstein Theorem that this is a symplectic form.

**Definition 1.7.** A **submanifold** of  $M$  is a manifold  $X$  which comes with a closed embedding  $\iota : X \hookrightarrow M$ , i.e. a proper injective immersion.

**Definition 1.8.** Let  $(M, \omega)$  be a  $2n$ -dimensional symplectic manifold. A submanifold  $Y$  of  $M$  is called a **Lagrangian submanifold** if at each point  $p \in Y$  the tangent space  $T_p Y$  is a Lagrangian subspace of  $T_p M$ , i.e.  $\omega_p|_{T_p Y} \equiv 0$  and  $\dim(T_p Y) = \frac{1}{2} \dim(T_p M)$ .

**Example 1.4.** Let  $X$  be a manifold and  $M = T^*X$  be the cotangent bundle. The zero section is the set

$$X_0 := \{(x, \xi) \in T^*X \mid \xi = 0 \text{ in } T_x^*X\}.$$

This is just the injection  $X \hookrightarrow M$ . We clearly have that  $\alpha = \sum \xi_i dx_i$  restricts to 0 on  $X_0$  and therefore  $\omega|_{X_0} \equiv 0$ .

**Theorem 1.4.** Let  $(M_1, \omega_1), (M_2, \omega_2)$  be two  $2n$ -dimensional symplectic manifolds. A diffeomorphism  $\varphi : M_1 \rightarrow M_2$  is a symplectomorphism if and only if  $\Gamma_\varphi$  is a Lagrangian submanifold of  $(M_1 \times M_2, \tilde{\omega})$ , where  $\tilde{\omega} = pr_1^* \omega_1 - pr_2^* \omega_2$ .

*Proof.* Let

$$\begin{aligned} \gamma : M_1 &\rightarrow M_1 \times M_2 \\ v &\mapsto (v, \varphi(v)) \end{aligned}$$

we have that  $\Gamma_\varphi$  is Lagrangian if and only if  $\gamma^* \tilde{\omega} \equiv 0$ . But we have that

$$\begin{aligned} \gamma^* \tilde{\omega} &= \gamma^* pr_1^* \omega_1 - \gamma^* pr_2^* \omega_2 \\ &= (pr_1 \circ \gamma)^* \omega_1 - (pr_2 \circ \gamma)^* \omega_2. \end{aligned}$$

But  $pr_1 \circ \gamma$  is the identity map and  $pr_1 \circ \gamma = \varphi$  and therefore

$$\gamma^* \tilde{\omega} \equiv 0 \Leftrightarrow \varphi^* \omega_2 = \omega_1.$$

□

**Definition 1.9.** Let  $(M_1, \omega_1), (M_2, \omega_2)$  be two symplectic manifolds. A **Lagrangian correspondence** from  $M_1 \rightarrow M_2$  is a Lagrangian submanifold of  $(M_1 \times M_2, \tilde{\omega})$ .